# Draft of the 2021 Rubrics for Rescue Line and Maze

## Video

#### Requirements

#### To submit:

- Teams must submit the videos as .mp4 files to the competition submission system by June 15th (UTC: 23:59:59)

#### What is in the video?

Some pre-defined arenas no bigger than 4 tiles x 6 tiles (approximately 4ft x 6ft or 120cm x 180cm) will be released in the middle of May. Teams must choose three pre-defined arenas to run. Teams will be required to: 1) Replicate the arena configuration. (Do note: you may utilize any materials to make this happen. Be creative! Field quality just needs to be good enough for you to demonstrate the robot's performance. The field quality itself will not be scored.

2) Record their robot execution as it would have been under the Official Rules. For example you will have to execute your robot run as if you were the referee, e.g. call Lack of Progress.

3) For each field, record a sequence of 3 runs in one continuous video. The goal is to see the reliability of your robot's performance. To make sure that the runs are consecutive, you need to provide a visible clock in the frame.

\*\* Any video with clear sign of modification will be disregarded.

### Documentation

Mechanical design and manufacturing					
Key Elements	C	1-2	3-4	5-6	7-8
non-commercial-kit		Commercial kit with 1 component from another manufacturer (e.g. all LEGO, or all MakeBlock)	Commercial kit with 2+ functional components from another manufacturer	Commercial Controller, and sensors devices are selected individually. Not coming from a commercial kit. Somewhat work well together	Prev + work well together.
informative diagrams		Very little images/diagrams to illustrate the mechanical design and structure	Demonstrate good effort in having some diagrams to show mechanical design and structure, and provide somewhat quantitative data.	Had clear diagrams to Show sound design and structure, with illustration including flowchart, diagram, sample data, etc. Presented thorough analysis with quantifiable data	Prev + replicable model for others to learn from
quantative data support		very little illustration quantitative data to support how well the robot mechanics work.	Demonstrate some effort in illustrating quantitative data to support how well the robot mechanics work.	Give viewers clear illustration on quantitative data to support how well the robot mechanics work.	Prev + replicable model for others to learn from
sub-module design and workability		Includes some level of how the system is composed of interacting parts (sub- modules), but confusing, i.e. some sign of modularization.	Give good amount of design proof to provide the view of the entire system and its interacting parts (modules). Had somewhat like pathways of interaction among the parts with diagrams.	interfaces and their interacting parts, and pathways with diagrams and design	Prev + replicable model for others to learn from

Electronic design and manuf	actur	ing			
Key Elements	0	1-2	3-4	5-6	7-8
non-commercial-kit		commercial kit with 0-1 outside the box nechanical contraptions.	Commercial kit with 2 or more functional outside the box devices.	Commercial Controller, and sensors devices are selected individually. Not coming from a kit. Somewhat work well together	Innovative design with working solution
Design and implementation	1 1	ustomized circuit board, but lack of xplanation	custom circuit board, but show some understanding	Innovative design but just somewhat working	Prev + Innovative design as working solution
with images/schematics	1 1	ery little images/diagrams to illustrate the lectronic design, schematics.	Demonstrate good effort in having some diagrams to show the electronic design, schematics. Give viewers a somewhat understanding, but materials are confusing.	Prev + materials are clear to understand.	Prev + replicable model for others to learn from
with quantitative support	1 1	ery little illustration quantitative data to upport how well the electronic design work	Demonstrate some effort in illustrating quantitative data to support how well the electronic design work.	Prev + explain results and observations from the data.	Prev + replicable model for others to learn from
Projects Planning - from Desi	ian. ta	Deployment			
Key Elements		1-2	3-4	5-6	7-8
Milestones /Project plan	p	ttle sign of stages of milestones, vague lanning. Most tasks are done at moment ecision.	Show signs of stages with milestones, project planning, but lack of sign for used as a guide	Show signs of stages with milestones, project	Clear progressive milestones with teams assignment, and used as an overarching guide.
logical organization of materials	1 1	ttempt to have a good flow of information, ut lack a logical progression. Confusing.	Major aspects of the analysis or recommendations are present, but lack of Diagrams or graphics	The underlying logic is clearly articulated and easy to follow. Content are concise but informative for reader's comprehension. Diagrams or analyses enhance and clarify presentation of ideas	So well done that it can be used as learning model materials for others.
Reliability Test Plan and Quality Assurance	0	how some kind of test cases planning, but nly simple ones, and lacking of keeping eliability in mind	Shows detailed reliability tests cases in mind.	Clearly Shows thoughtful Tests Plans and quality assurance, and integration plan.	Prev + optimization plan.
Data Collection, Prototyping and analysis	ill	ttle sign of prototyping design ideas. Lack of lustration on systematic data collection nethods and analysis	Good attempt to show prototyping on intended ideas. Attempted to show illustration of systematic data collection methods and analysis, but vague.	Clear attempt on Prototyping and even tested in multiple conditions/trials.	Prev + Innovative systemic and computational methods. Role model engineering skill.
Integration Plan	Li	ttle sign of integration plan	Show good effort in integration plan, but not executed well.	Clearly shows well-illustrated integration plan, but not executed well.	Prev + clearly executed well.
Recognize Constraints	n	alk about interesting constraints, but does ot how further insight as how that influence our project.	Clearly show how the constraints influence the success or failure of your project	Prev + show vision as how to work around the constraints IF resources are available.	Innovative way to get around the constraints
Engineering Journal					
Key Elements	0	1-2	3-4	5-6	7

Daily logs showing Project progress, experiments, etc.	Show sign of work progression, such as little daily log information on experiments. Lacking useful links to details. Most likely it is after- thought work.		. ,	Creative way to log information to help communicate ideas among members, and stimulate further thinking
Record for easy lookup and reference	, ,	allow team for easy lookup of needed information, but content is unorganized.	Show good attempt to organize the content to allow team for easy lookup of needed information, and content is somewhat organized.	Very well -organized, and creative ways for easy lookup, such as important glossary of ideas/issues/etc.
Usefulness and repeatability	Provide Engineering Journal, but little meaningful illustration of progress such as troubleshooting, problems, solutions.	Provide Engineering Journal, with meaningful illustration of progress, including some trouble shooting, issues and solutions.	proper reference	Prev + with great clarity, including reference links to further details and experiments, etc., that allowing team members to verify each other's work, and reproduce design work.

Presentation					
Mechanical design and man	ufa	cturing			
Key Elements	0	1-2	3-4	5-6	7-8
Presentation of the design		Only few unclear pictures or drawings with no additional value through the explanation	Some pictures and/or drawings of the current design with some effort in explaining the functionality	Pictures and drawings of the current design of the robot and explanation of the functionality	Pictures and drawings of the current design of the robot and an easy to follow and insightful explanation of the mechanical functionality
Optimisation Process (roughly within two years)		Only incomplete, sporadic updates on the steps in the design process with no clear method recognizable	Some meaningful updates on the steps in their design process with some hints to a methodical approach	Pictures and drawings from multiple steps in the design process and some explanation of their method to improve the robots mechanical design	Pictures and drawings from different steps in the design process and explanation of highlights in the process and their method used to improve the robots mechanical design
non-commercial-kit		Commercial kit with 1 component from another manufacturer (e.g. all LEGO, or all MakeBlock)	Commercial kit with 2+ functional components from another manufacturer	Commercial Controller, and sensors devices are selected individually. Not coming from a commercial kit. Somewhat work well together	Prev+ work well together.
Electronic design and manuf	fact	uring			
Key Elements	0	1-2	3-4	5-6	7-8
Presentation of the design		Only few unclear pictures or drawings with no additional value through the explanation	Some pictures and/or drawings of the current design with some effort in explaining the functionality	Pictures and drawings of the current design of the electronics and explanation of the functionality	Detailed drawings of custom electronic hardware and explanation of its functionality
Optimisation Process (roughly within two years)		Only incomplete, sporadic updates on the steps in the design process with no clear method recognizable	Some meaningful updates on the steps in their design process with some hints to a methodical approach	Documentation from multiple steps in the design process and some explanation of their method to improve the robot's electronics	Documentation from different steps in the design process of the electronics and explanation of their method used to improve the electronics on the robot

			1	1
non-commercial-kit	Commercial kit with 0-1 outside the box	Commercial kit with 2+ functional outside	Commercial Controller, and sensors devices	Innovative design with working solution
	mechanical contraptions.	the box devices.	are selected individually. Not coming from a	
Otanta ana ana d Diana ina a			kit. Somewhat work well together	
Strategy and Planning				
Key Elements	0 1-2			7-8
Plan for main task (following	Some plan to tackle the main task with no		Robust plan for the main task with somewhat	
the line/navigating the maze)	optimization process recognizable	some test data with no clear optimization	quanitfiable data from tests and a rough optimization method	with quantifiable data form tests and a clear
		process recognizable		optimization method which led to the plan
Plan for uncommon scenarios	Only few uncommon scenarios have been tested and encountered problems were	Testing procedures include some uncommon scenarios and most of them	Testing procedures include plan for uncommon scenarios in the arena and most	Testing procedures include comprehensive plan for uncommon scenarios in the arena
scendrios	solved with conventional approaches	have been solved with conventional	of the problems have been solved with	and some encountered problems have been
		approaches	conventional approaches	solved with innovative ideas
Workflow and Teamwork				1
Key Elements	0 1-2	2 3-4	5-6	7-8
Allocation of tasks in the	No clear structure in the team but every	Some specialization within the team but no	Structure in the team with a role for every	Clear structure within the team with roles for
team, and team	team member has contributed to the result	clear structure and responsibilities	member and some measures to reach the	every member and processes to collaborate
cohesiveness			design goal	towards a common design goal. Each
				member contributes in a valuable way to the
				project. All members always attended
				meetings and met deadlines for deliverables.
Reliability				
Key Elements	0 1-2	2 3-4	5-6	7-8
Optimisation Process	Rough idea of a method to improve the	Testing method with a clear goal but only	Implementation of a testing method with	Implementation of a clear testing
	robots weaknesses with no quantifiable data		somewhat quantifiable data	methodology with problem identification
		data		and solutions with quantifiable data
Innovations			1	
Key Elements	0 1-2	3-4	5-6	7-8
Learnings from previous	Only vague analysis of previous	Some analysis of previous performance with	Analysis of their performance at previous	Analysis of their performance at previous
competitions (for previous	performances and no real conclusions for	some ideas to improve their preparation	competitions and multiple ideas to improve	competitions and application of their
participants)	this year's competition		their performance and preparation	experience to this year's competition
Overall approach to the	Show little analysis of the task and no	Superficial analysis of the task and some	Analysis of the task and a somewhat	Analysis of the task and methodical
problem (for new	meaningful preparation method is derived	ideas for preparing for the competition	methodical approach to the preparation	approach to the preparation for the
participants)				competition
Technological Innovations	Slight improvement of the robots	Multiple innovative ideas in multiple areas of	Meaningful innovation in one area or	Meaningful innovations in multiple areas of
	performance under specific circumstances	the robot lead to some improvement in	multiple smaller innovations that improve	the robot that work together and contribute
	due to some innovative ideas	performance	the robots performance	significantly to the team's performance
Sharing			T	
Key Elements	0 1-2			
Sharing their knowledge with	Documentation of their engineering process	Documentation of their engineering process	Open sourcing of code or hardware design	Open sourcing of their code and hardware
the community	online	online and sharing some ideas of their code	with some effort in publishing meaningful	design and providing comprehensive public
		and hardware design	documentation	documentation that allows others to
				replicate their work

# Interview

Requirements:	
Live Presentation:	This will be similar to a Technical Talk where you will do an oral presentation of your robot.
	If you will not be able to present it in English, please make sure to specify that at the time of registration!
	Be creative! Best opportunity to showcase your innovation.
Interview	Questions may include:
	- Anything pertaining to all materials that you have submitted.
	- May be asked to demonstrate how well your robot works in some subsets of challenges.
	There will be a few small surprise challenges. Make sure you will attend the Interview with:
	- your fully functional robot
	- minimum one of the fields that you put in your video.
	- Materials that you use for creating the fields such as:
	- For Rescue line: green squares (for intersection), black tape, obstacle, etc.
	- For Rescue maze: Walls elements such as wall panels, various victims elements that can be moved around.